









# Visual Perception Framework for Human-care Service Robots

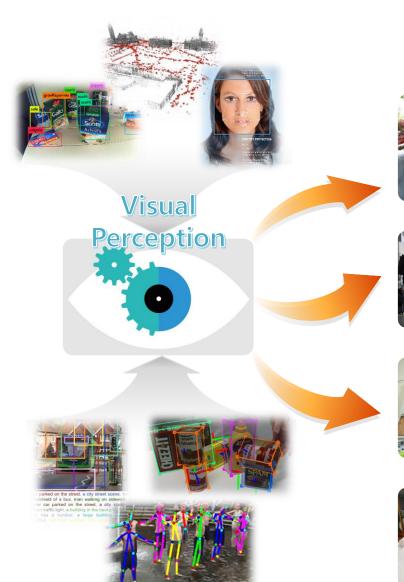
Chung-Yeon Lee<sup>1,2</sup>, Hyundo Lee<sup>1,2</sup>, Injune Hwang<sup>2</sup>, Byoung-Tak Zhang<sup>1,2</sup> Surromind Robotics<sup>1</sup>, Seoul National University<sup>2</sup>

### 1. Introduction

#### **Service Robots**







#### **Real-World Scenarios**











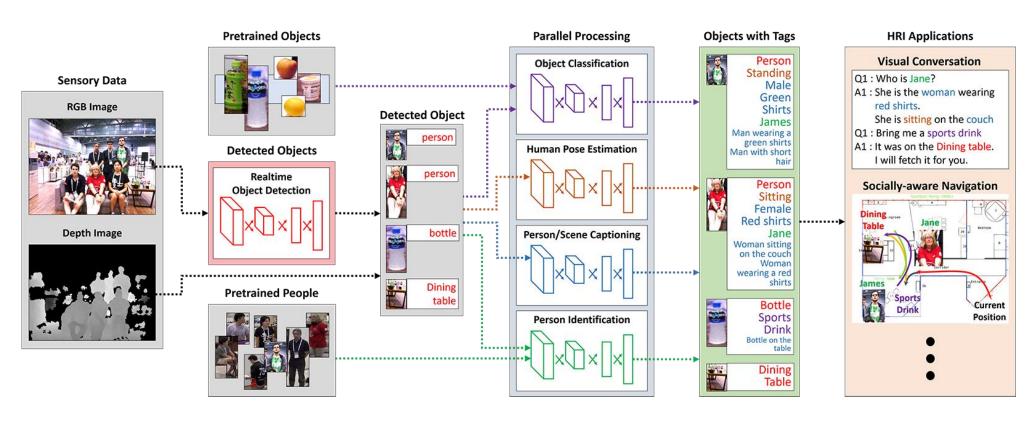
RoboCup 2017 Nagoya Japan



RoboCup 2018
MONTRÉAL CANADA



## 2. Visual Perception Framework













#### 3. Evaluations on Real-world Scenarios

- Restaurant (Pepper)
- Cock-tail Party (Pepper)
- Tour Guide (Pepper)
- Question and Answering (Pepper)
- Help Me Carry (Pepper)
- General-Purpose Services (Pepper)
- Bring Me (HSR)
- Tidy-up the Room (HSR)
- Elderly-Care Service (HSR)

