

# Predictive Driving For Human Passenger Comfortable Navigation

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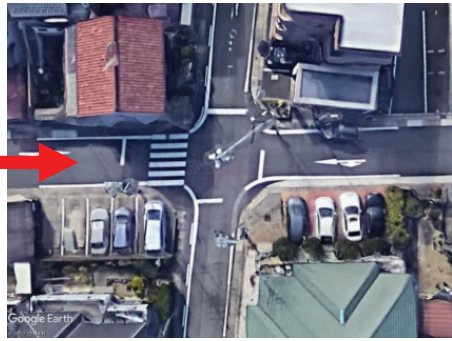
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# Introduction

Drive proactively expecting potential moving obstacles in blind intersections or locations with bad visibility

# Introduction

- Drive proactively expecting the unexpected in blind intersections or locations with bad visibility

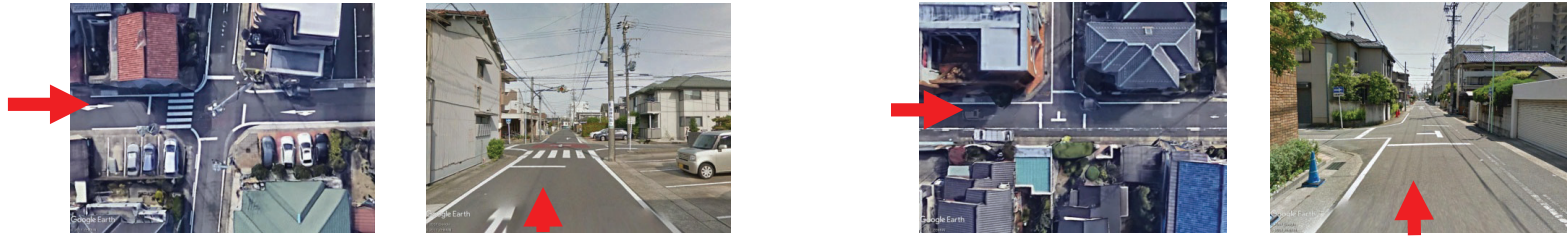


# Introduction



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  - Many roads do not have lanes
  - Where to drive in the road?
  - At what velocity does the vehicle drive?

# Objective

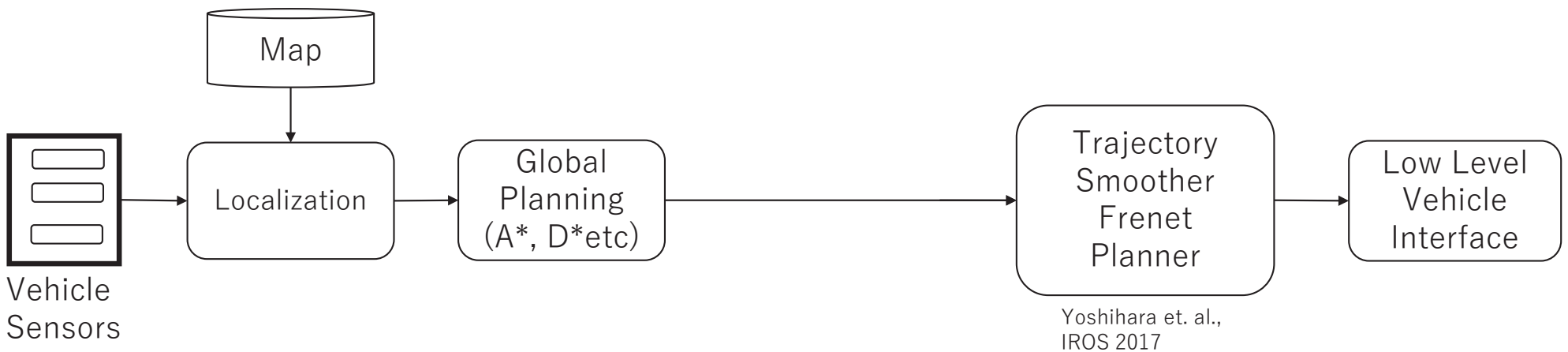
- Have autonomous driving that can learn from human skilled drivers

# Objective

- Have autonomous driving that can learn from human skilled drivers
  - Proactively safe
  - Smooth
  - Considered for others: Pedestrians, bicycles, vehicles
- The best human drivers anticipate, they do not react

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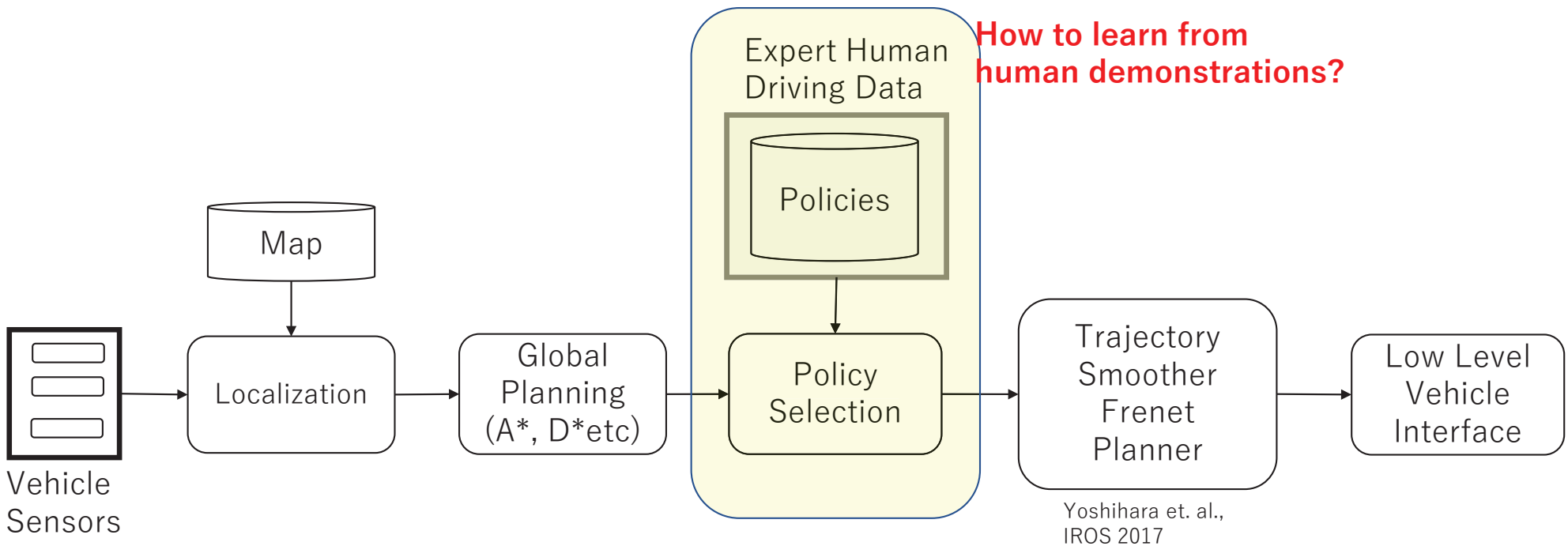
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# Predictive Driving

