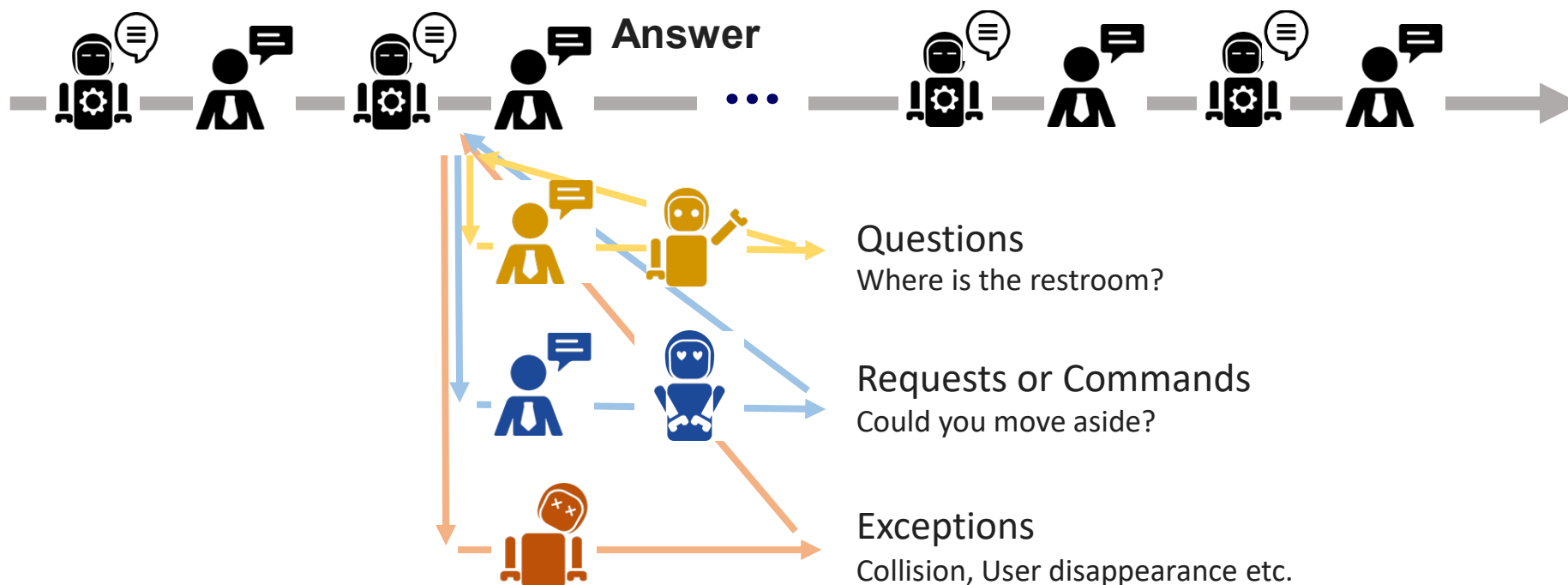


How can robots fully respond to off-scenario inputs?



How can we let the service designer focus only on designing the scenarios, not needing to consider off-scenario interruptions?